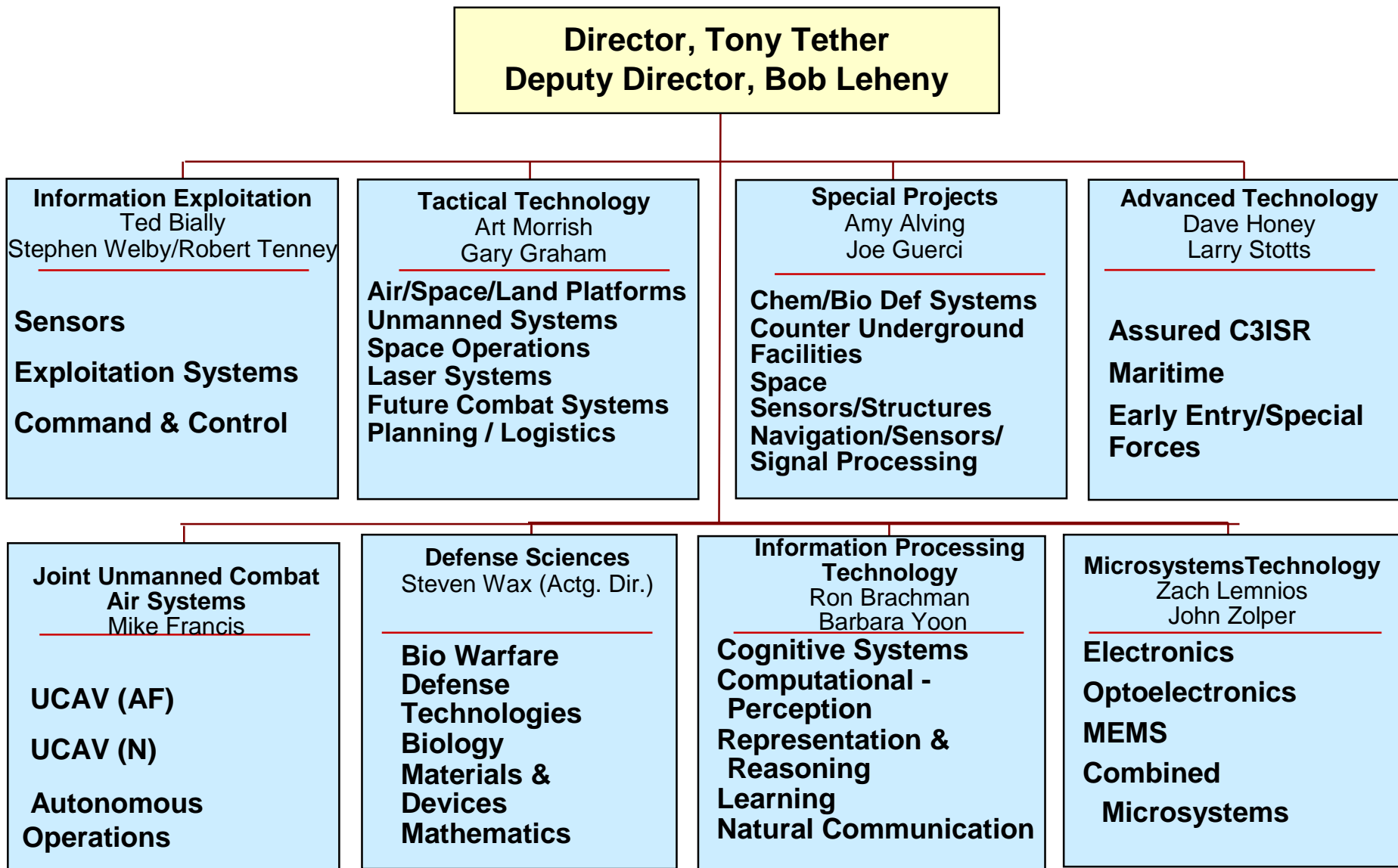


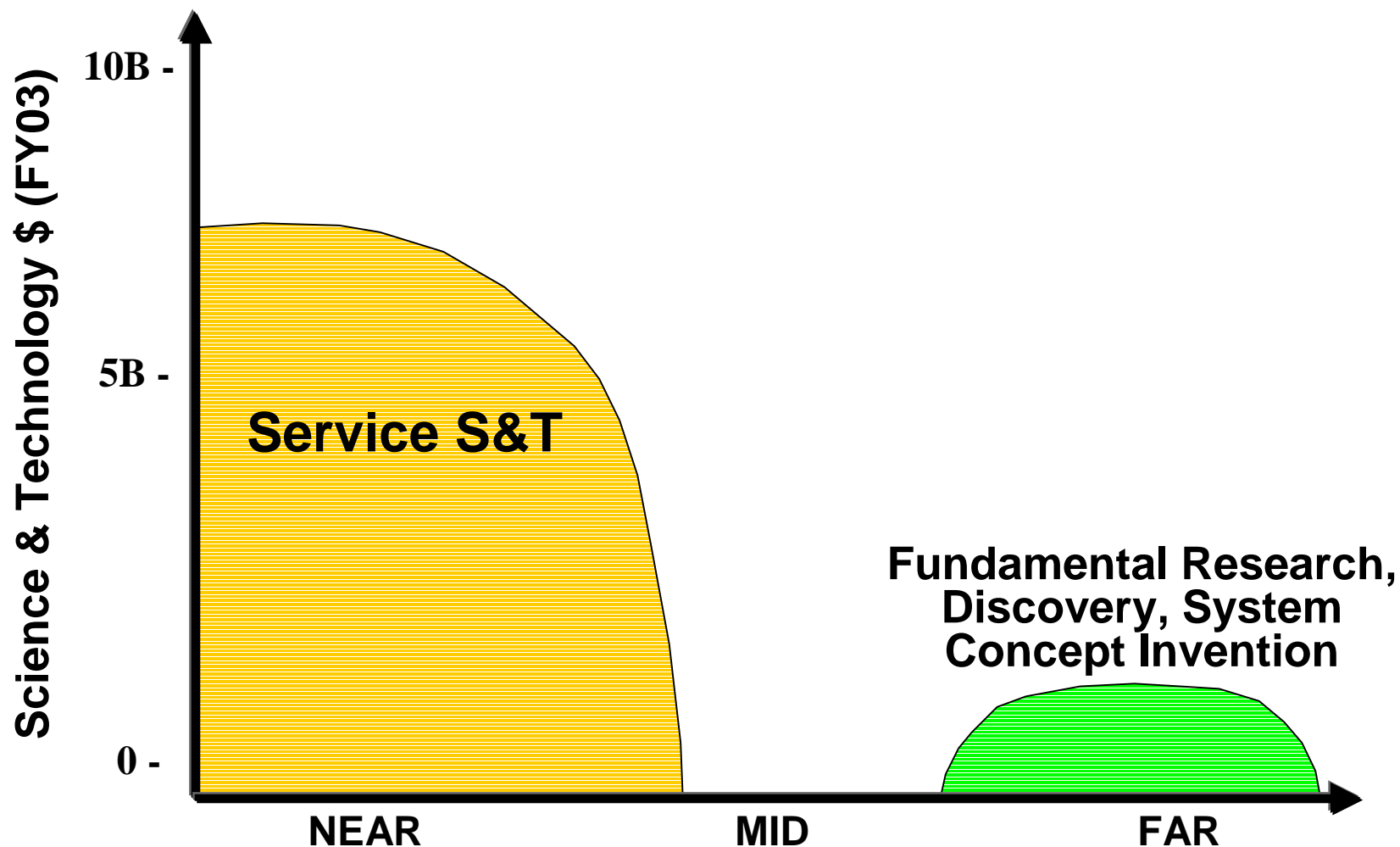
ICHOR Industry Day



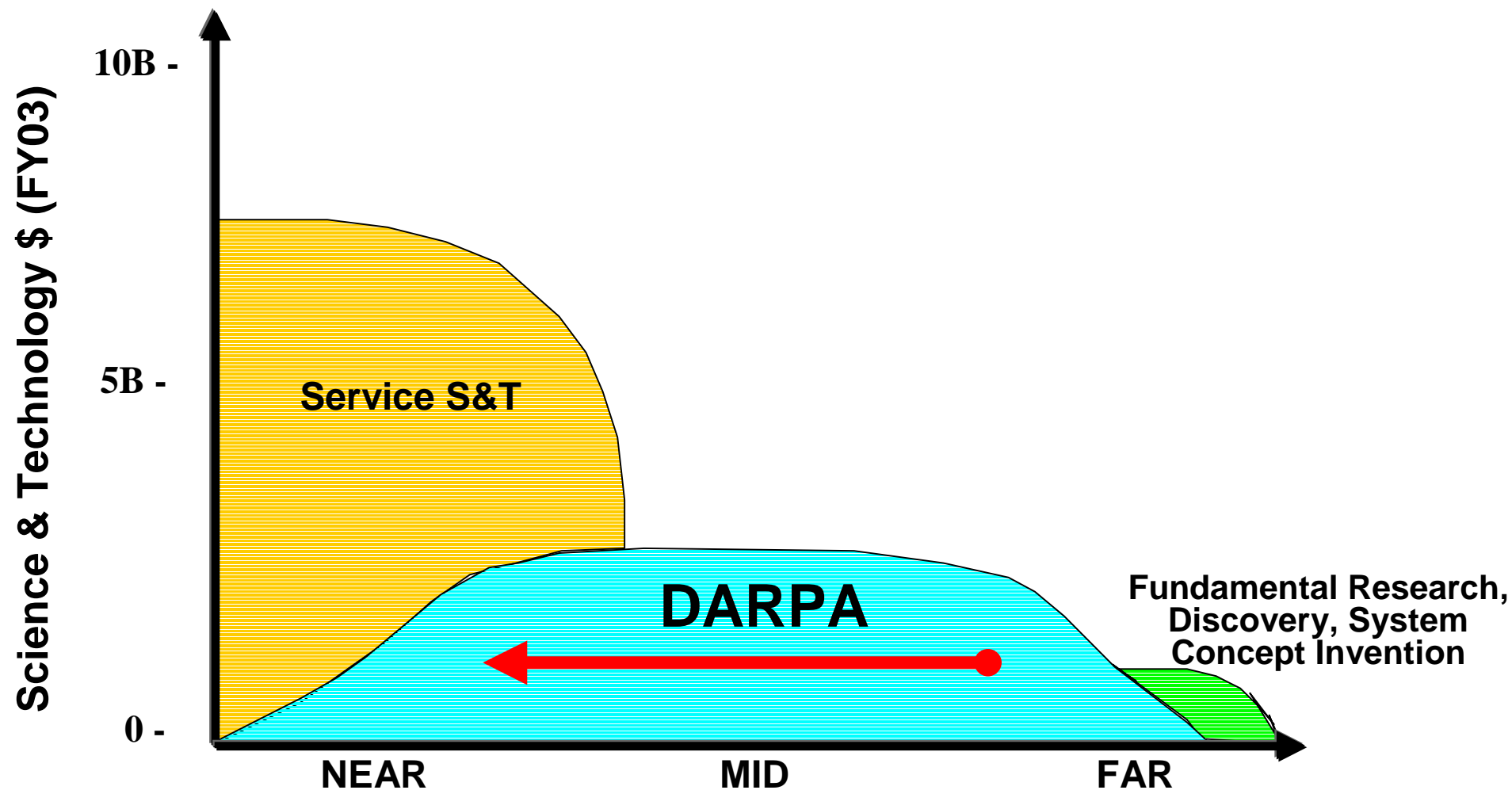
Arlington, VA
December 05, 2003



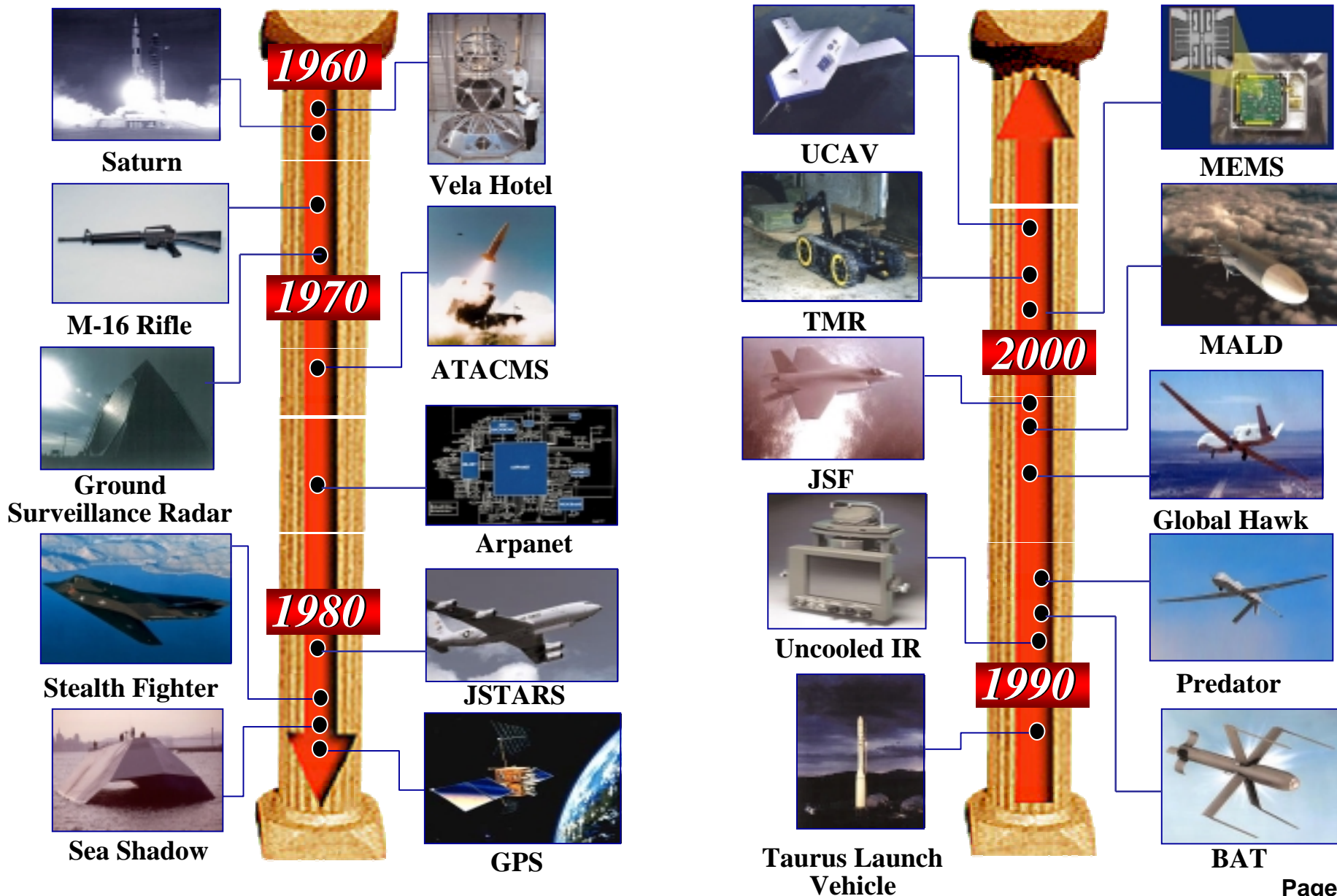
DARPA Role in Science and Technology



DARPA Role in Science and Technology







DARPA Accomplishments



Investments Today for Future Capabilities

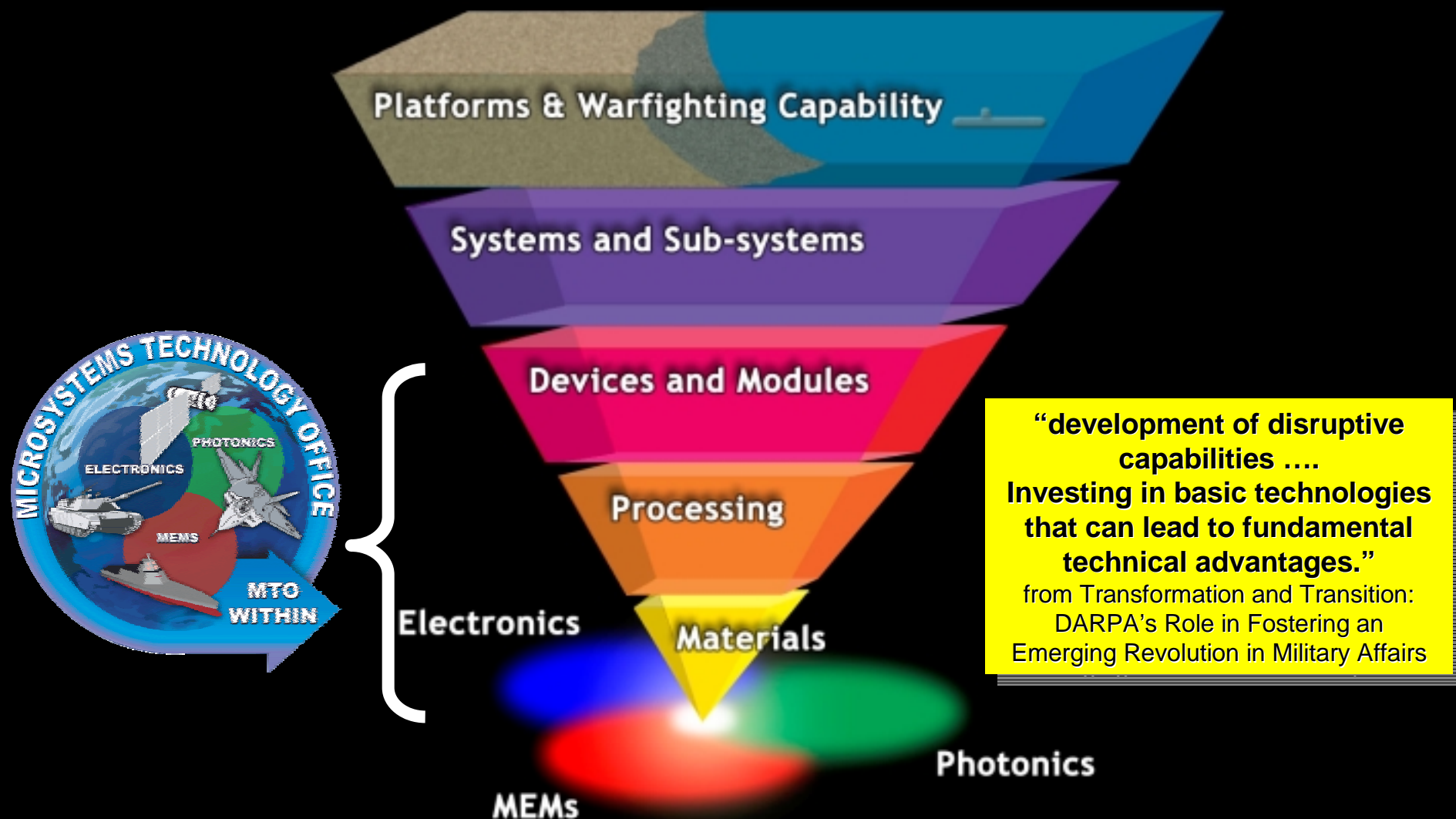
- **Detection, Precision ID, Tracking, and Destruction of Elusive Surface Targets**
- **Characterization of Underground Structures**
- **Networked Manned & Unmanned Systems**
- **Robust, Secure Self-Forming Tactical Networks**
- **Cognitive Systems**
- **Assured Use of Space**
- **Bio Revolution**

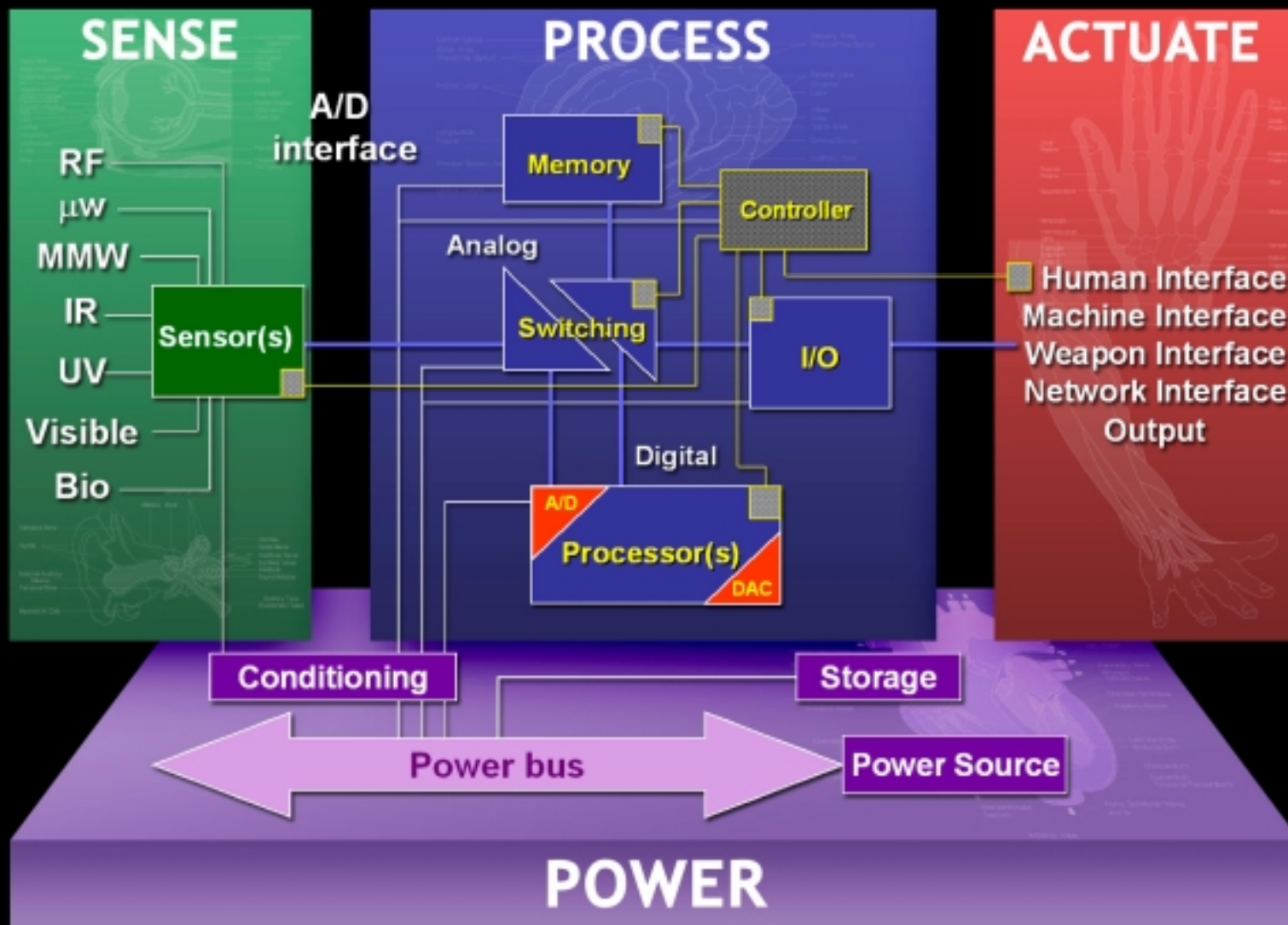
Develop, demonstrate and transition the key solid state technologies that enable dominant system concepts and capabilities for the Department of Defense

-  **Pushing the limits of scaling and integration**
-  **Microsystems for spectral exploitation and sensor dominance**
-  **Systems that intelligently interact with the environment**
-  **Tools that enable scaleable and affordable access to leading edge components**

DoD Access to Winning Microsystem Technology

MTO Enables Platform Capability





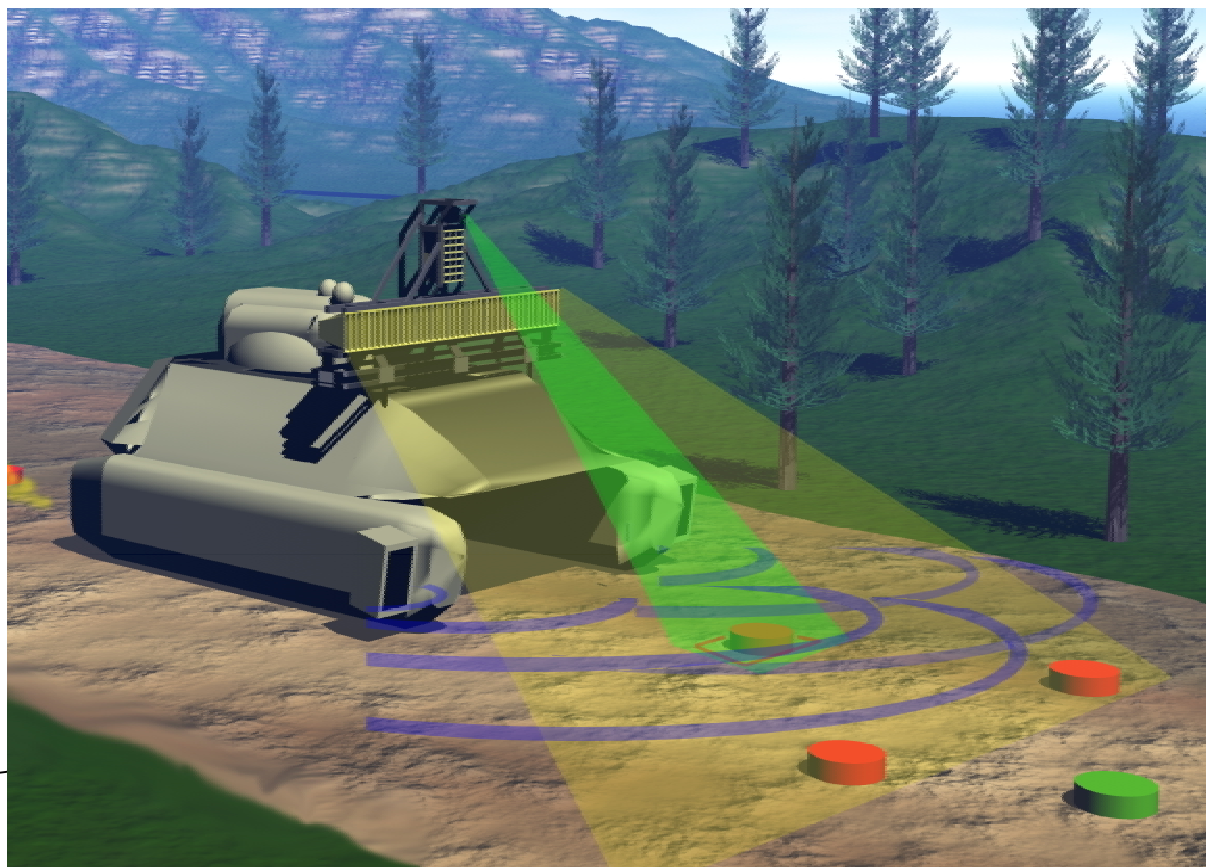
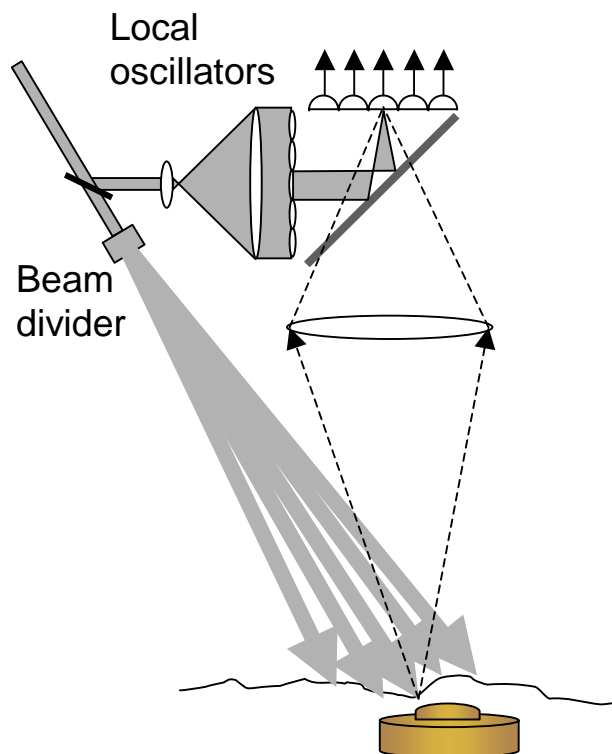


Chief Scientist, President, CTO, VC,
Entrepreneur, Banker

- Always looking for the next idea
- Creative and innovative
- Leader in the field
- Juggles ideas from industry, academia
- Always on the road
- Overloaded calendar
- Willing to take risk
- Articulate persuasive advocate of the idea

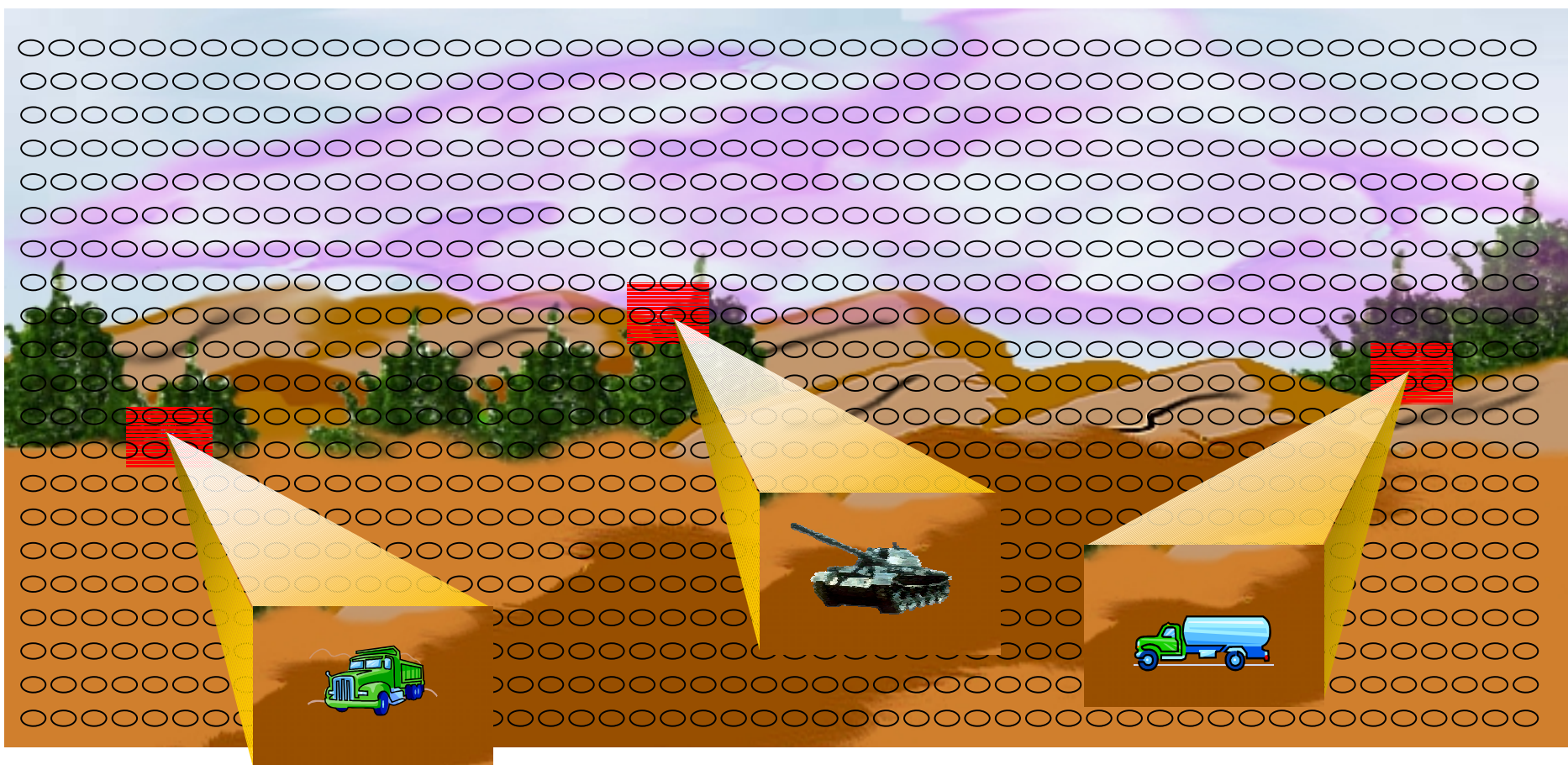


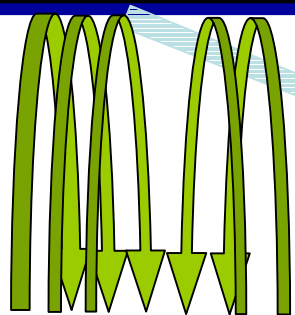
IMAGING COHERENT OPTICAL LASER RADAR



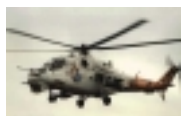
Current state of the art – single pixel, >40 sec per square meter
 Five meter road swath, vehicle advance rate = 0.018 km/hr
 With 1028 pixel ICHOR, vehicle advance up to **18 km/hour**
 Insertion into FCS

Threat Detection Using Large ICHOR Arrays





**Non-Line-of-Sight (NLOS) Helicopter
Detection via Rotor Wash Detection**

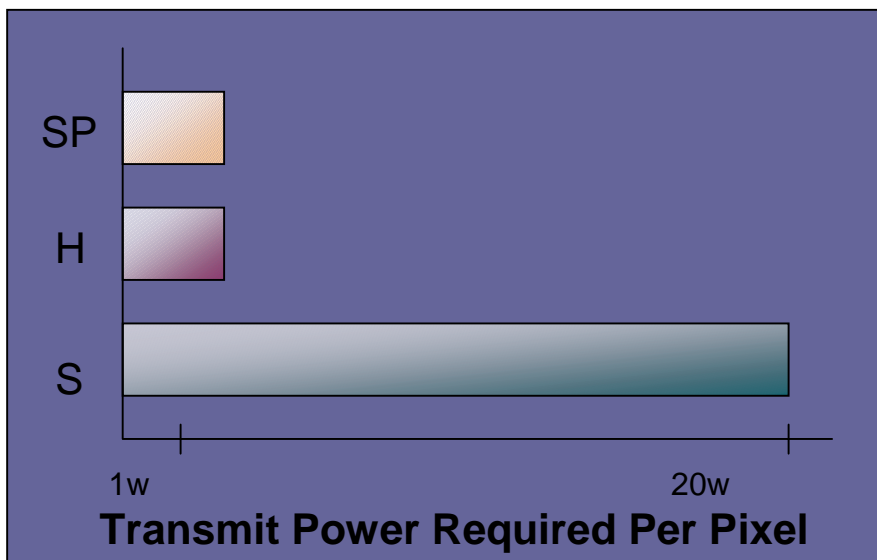
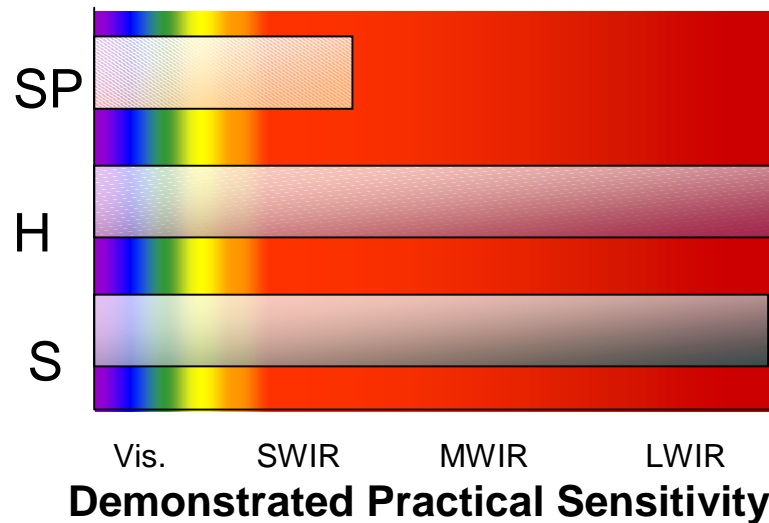
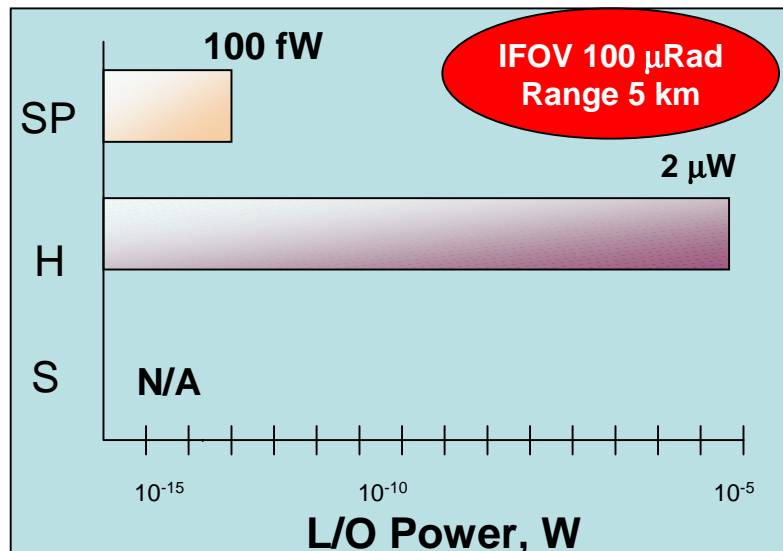





**Chem/Bio Cloud and Exhaust Plume
Detection and Characterization**



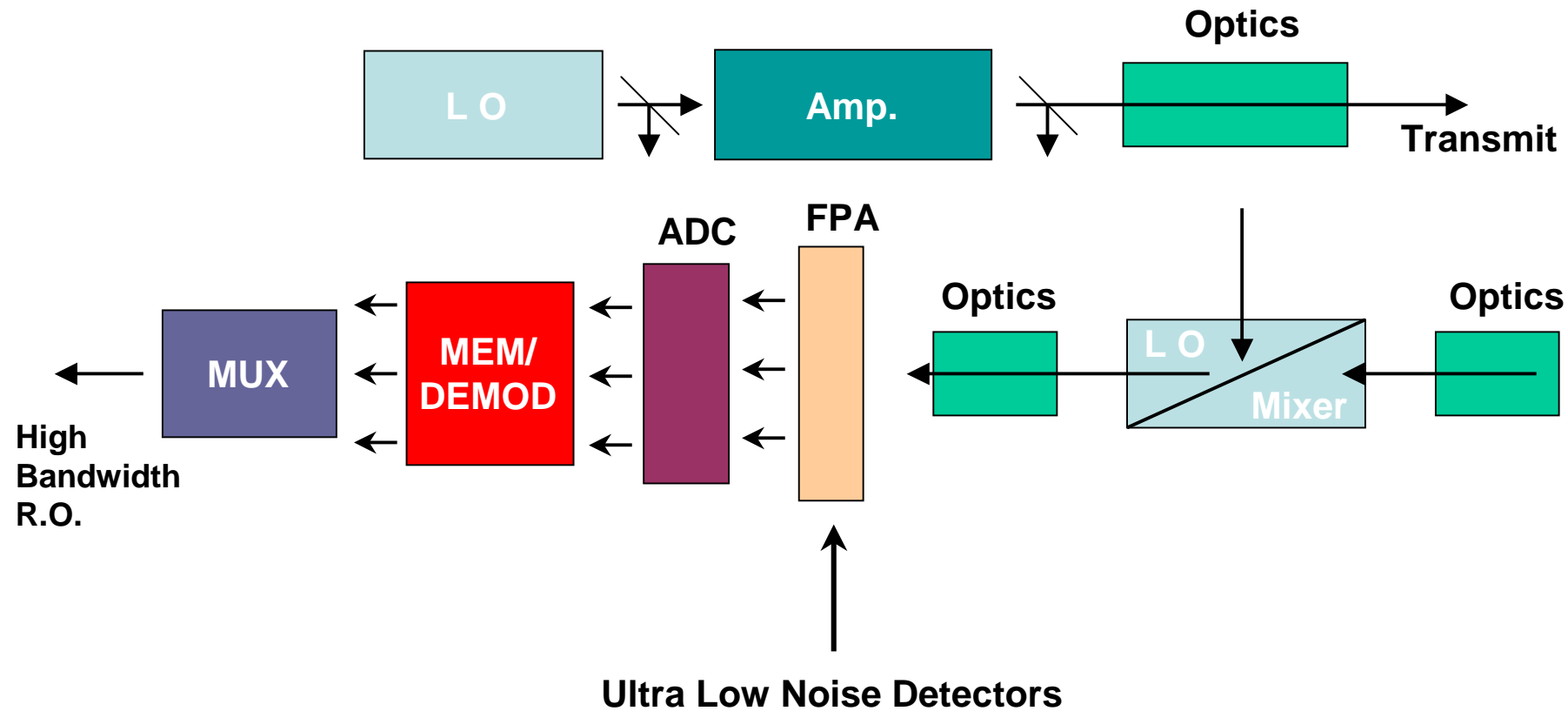
**Wind Field and
Turbulence Sensing**

Range Resolved Active Coherent Vibration Imaging

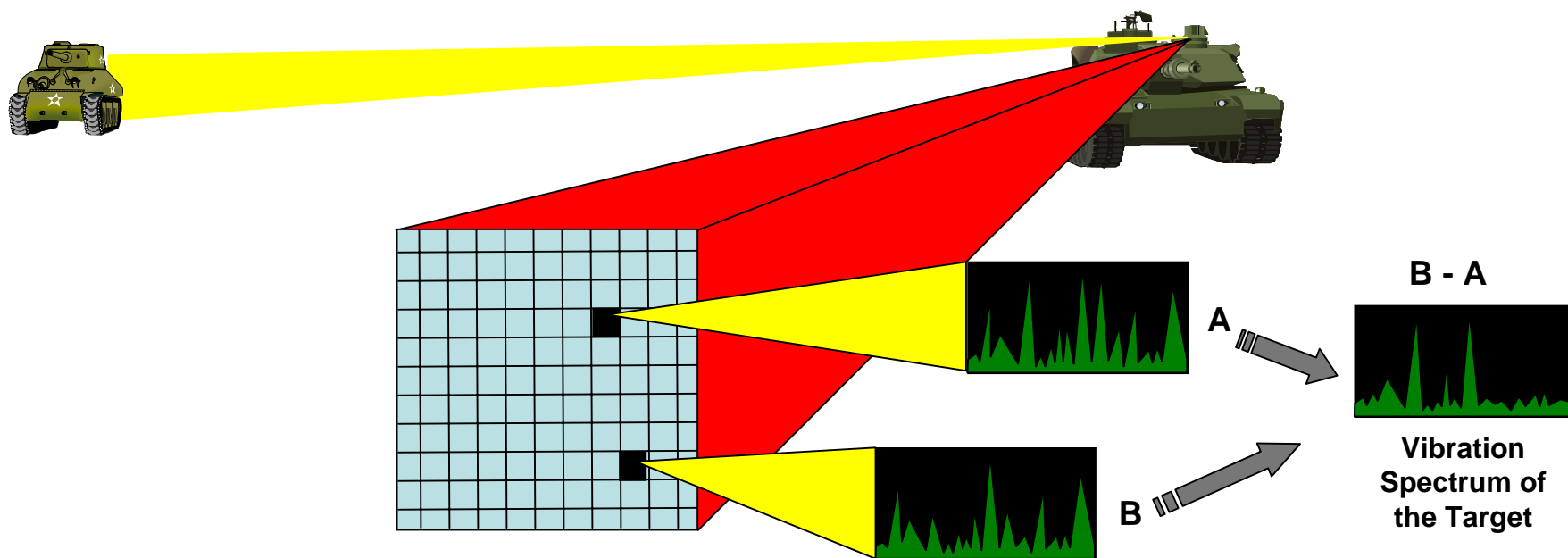


-  SP – Single Photon
-  H – Heterodyne
-  S – Speckle
- L/O – Local Oscillator

Basic Structure of Coherent High Speed Imager



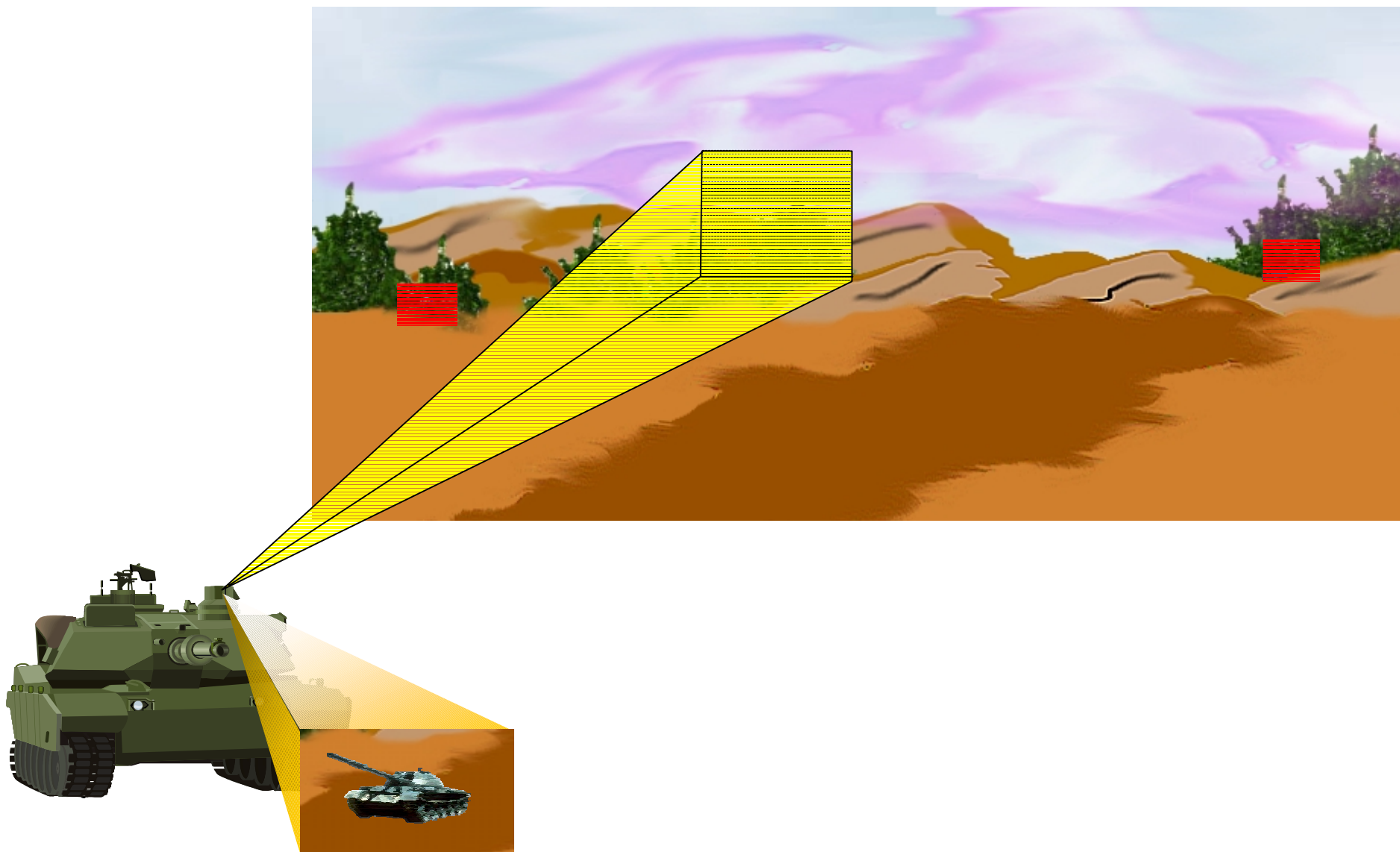
Program is basically technical development, that uses system demos to stay on track. The primary emphasis are; ultra low noise detectors (FPA, TIA & Pre-amp), high bandwidth cooperative processing on ROIC, and noise reducing optical design.



For a Sensor on a Vibrating Platform, Every Pixel Has the Platform's Vibrational Spectrum (Noise). Noise Reduction Techniques That Take Advantage of Simultaneous Detection at Many Pixels are Encouraged.



Threat Interrogation



ICHOR Go/No-Go Criteria

	Bandwidth	Pixel Count	Vibrational Frequencies	Vibrational Frequency Resolution	Velocity Sensitivity*	Low Displacement Limit
Phase I	100 MHz	≥ 100	DC-500 Hz	10 Hz	$10 \times \sigma$	100 nm
Phase II	500 MHz	≥ 500	DC-1 KHz	5 Hz	$3 \times \sigma$	10 nm
Phase III	1 GHz	≥ 1000	DC-2 KHz	1 Hz	σ	1 nm

* The vibrational sensitivity goal σ is listed in the classified Appendix.

The ideal proposal

- Pitches an integrated system meeting program sensitivity goals; supporting technology proposals will be considered if they offer leap-ahead technology.
- Contains sufficient modeling to demonstrate that the offeror will be able to meet the sensitivity goals of the program.
- Contains a coordinated plan to field test your system for each Phase of the program.

If two proposals have similar sensitivities and noise reduction, but one proposal gains sensitivity through cooling and the other through improved materials, the desired proposal would be the one that uses improved materials.

Integrated teams that contain a mix of universities, laboratories (government, FFRDC, etc.), component manufactures, and systems integrators, are encouraged.

BAA Timeline

